

Freshness and Reactivity Analysis in Globally Asynchronous Locally Time-Triggered Systems

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Brief introduction and main contributions

Context: real-time embedded systems (e.g. avionic systems)

- built as **functional chains** from sensors to actuators through real-time tasks
- **critical**

⇒ **need of formal verification methods**

⇒ **Main contributions:**

- a verification method for **end-to-end freshness and reactivity properties** along functional chains
- via a **Mixed Integer Linear Programming** formalization
- **scalable** approach

Outline

- 1 Context: real-time embedded systems
 - An avionic case-study
 - Generalization: models and hypotheses
- 2 Related approaches
 - Previous work
 - Contribution v.s. previous work
- 3 The freshness analysis method
 - General idea
 - Modeling
 - Results on the case study
- 4 Extension to reactivity requirements
- 5 Conclusion and next work

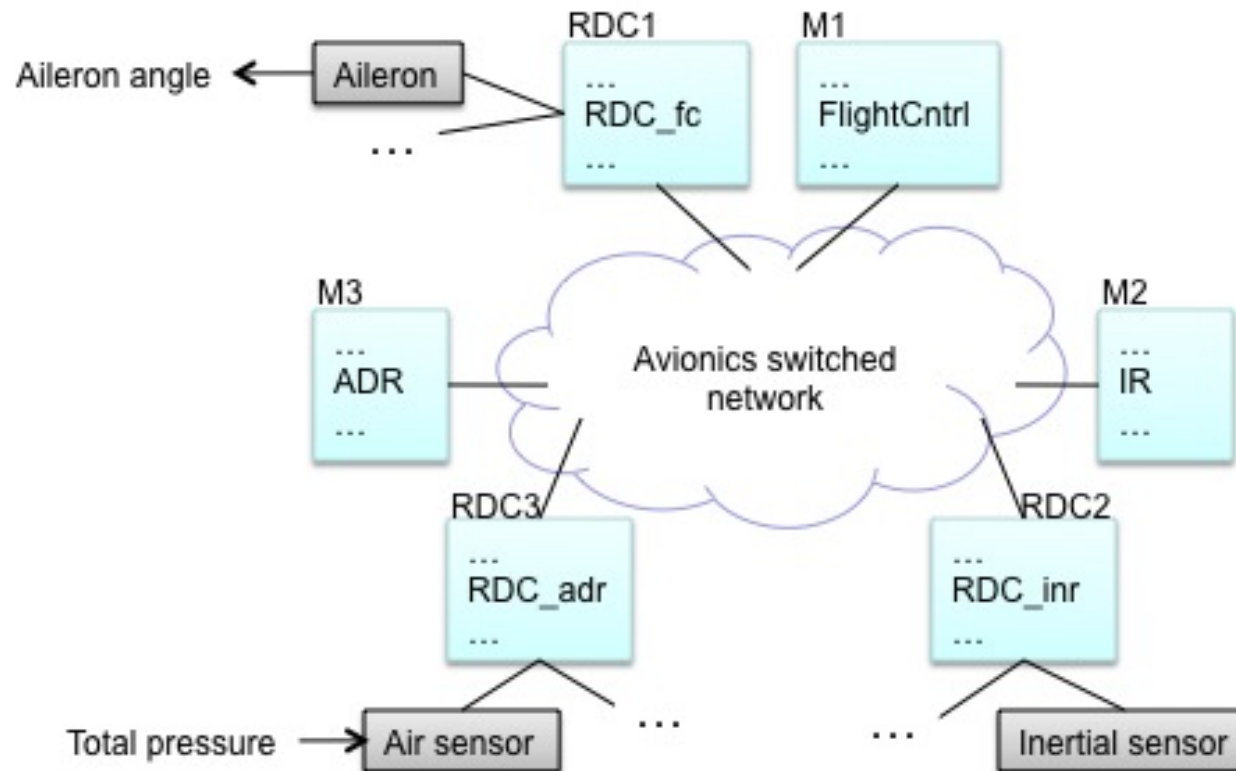
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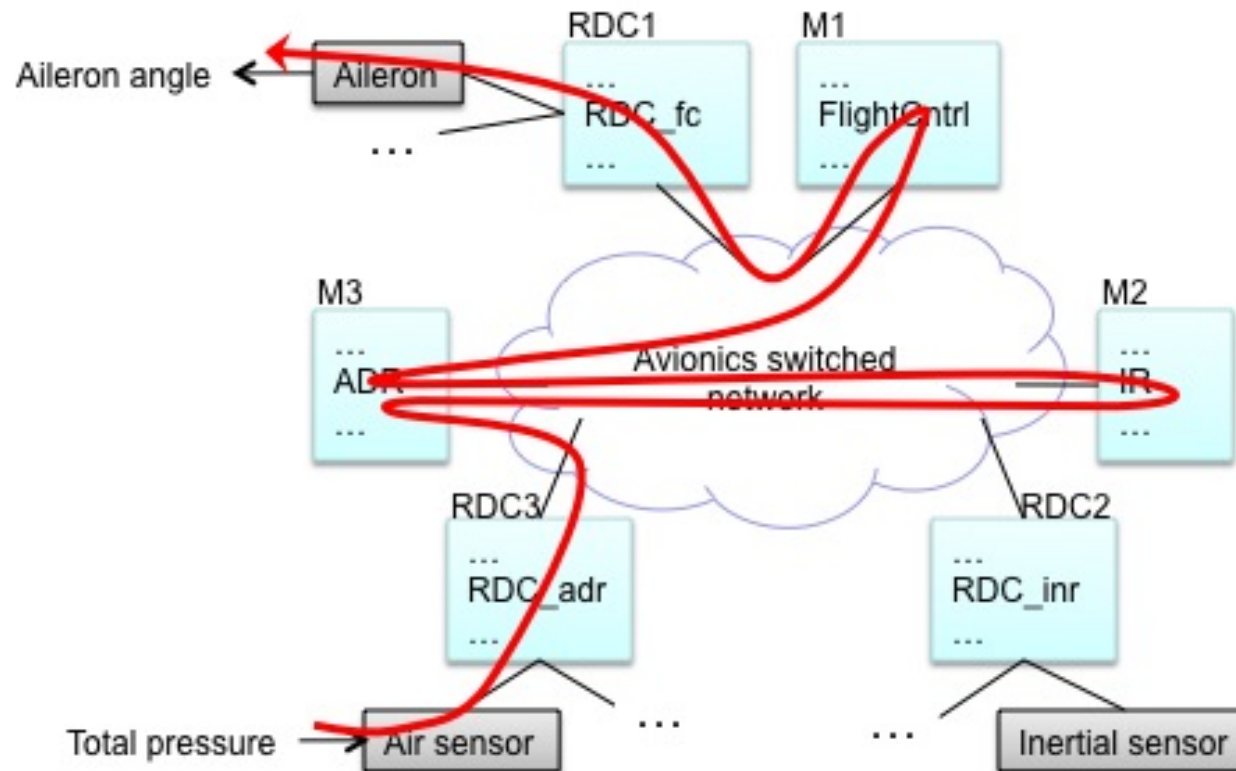
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A Flight Control Chain (extract)



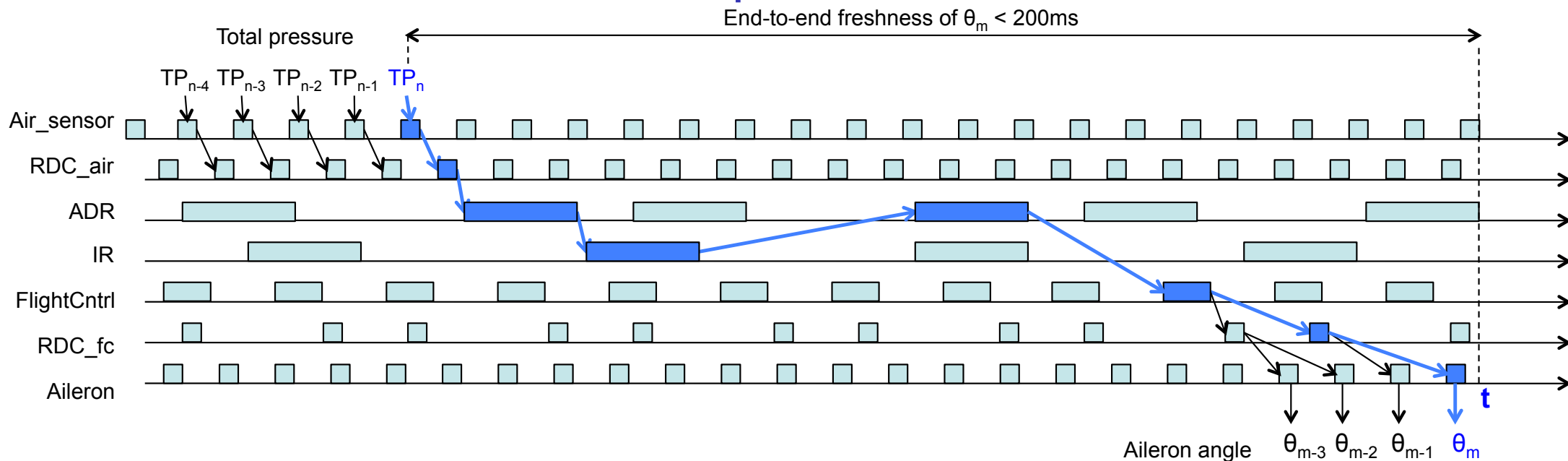
- computes the aileron angle w.r.t the current total pressure
- composed of 1 sensor, 1 actuator and 5 tasks mapped onto 5 processing modules
- tasks communicate through the avionics network

A Flight Control Chain (extract)



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End-to-end freshness requirement



Requirement:

- for any date t , let θ_m the current aileron angle (at t),
- let TP_n the sample on which θ_m depends
- then freshness requirement: $t - \text{date}(TP_n) < 200\text{ms}$

Freshness

$F(t) = t - \text{date}(TP_n)$ is the freshness of the θ_m at date t : the age of the output with respect to its related input

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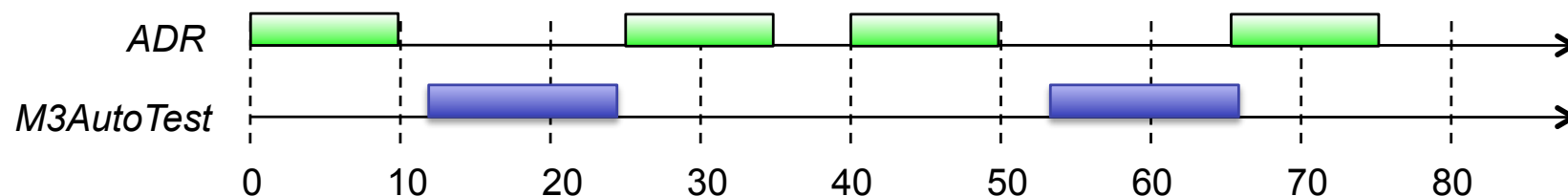
Model and hypotheses

System model:

- a set of periodic tasks $\Gamma = \{\tau_1, \dots, \tau_N\}$
- statically mapped onto a set of modules $\mathcal{M} = \{M_1, \dots, M_m\}$
- H_i is the hyper-period of the tasks mapped onto M_i .

Task model:

- each task τ_j on each module is characterized by a set of jobs $\{\tau_j(k)\}_{k=0\dots n_j}$ in the hyper-period of the module
- each job $\tau_j(k)$ is characterized by a timed interval $[b_j(k), e_j(k)]$ (static scheduling)



(example of module M_3)

Model and hypotheses

Communication model: tasks are assumed to communicate in an **asynchronous way**

- inputs are read at the beginning of the task
- outputs are produced at any time before the end of the task

Communication means:

- tasks running on the same module communicate through memory **without delay**
- tasks running on different modules communicate through a global network with **bounded traversal times**

Model and hypotheses

Global asynchronism: processing modules are **globally asynchronous**

- they can be shifted by an arbitrary amount of time.

⇒ Question: how to calculate the Worst Case Freshness (WCF) along a functional chain?

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Previous work

Local approaches

- The holistic approach (Tindell et al. (1994), Spuri (1996), ...)
 - Real-Time Calculus (Thiele et al. (2000))
- ⇒ **Can be pessimistic** since they consider worst case scenario locally on every component along the functional chain
- ⇒ **Lead to impossible scenarios**

Network analysis methods

- Network Calculus (Le Boudec et al. (2001))
 - Trajectory Approach (Martin et al. (2006))
- ⇒ **Only for network traversal time**

Previous work

Global approaches

- Global modeling by timed automata and model checking (Carcenac et al. (2006), Ning Ge et al. (2012))
 - ⇒ higher expressive power (more general temporal properties)
 - ⇒ however, suffer from the combinatorial explosion
 - ⇒ then, not efficient enough for realistic systems.

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The contribution v.s. the similar approaches

- to focus on **end-to-end freshness / reactivity** properties
 - to propose a **global** encoding as an Mixed Integer Linear Program
- ⇒ **less pessimistic** than local approaches
- ⇒ **more scalable** than model checking

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General idea

Principle

- to characterize all the possible behaviors of the functional chain with a set of **constraints**,
- to determine the worst case scenario among all these possible behaviors maximizing the **freshness criteria**
- can be done **automatically** by a solver.

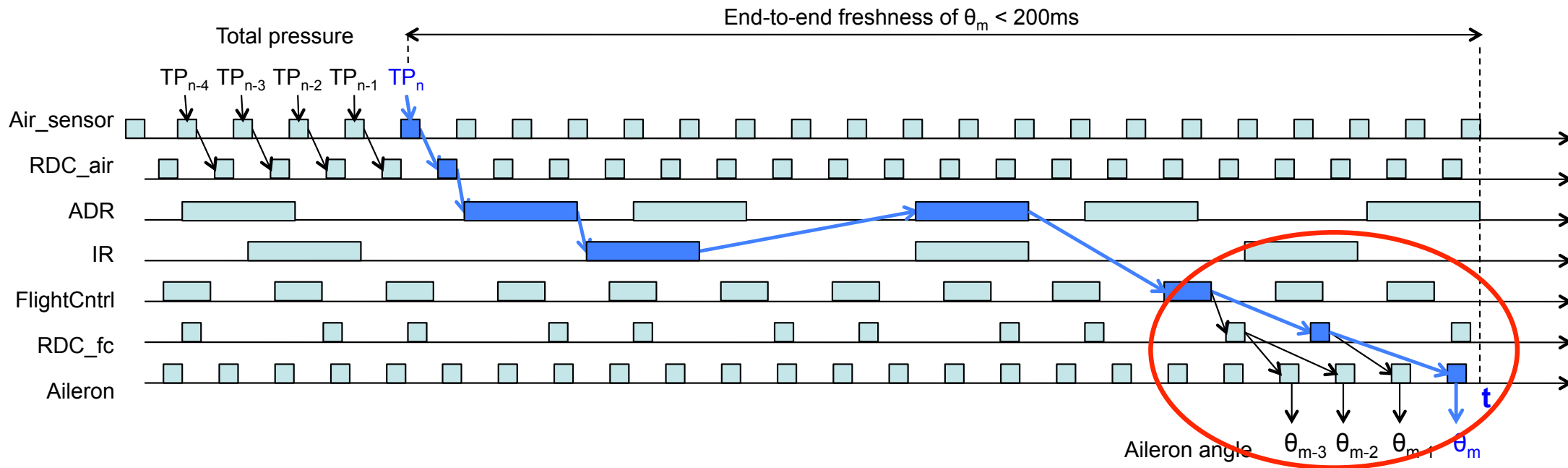
⇒ Challenge:

- to identify the variables of the modeling, and then the constraints defining accurately the behavior of the system
- in a scalable way

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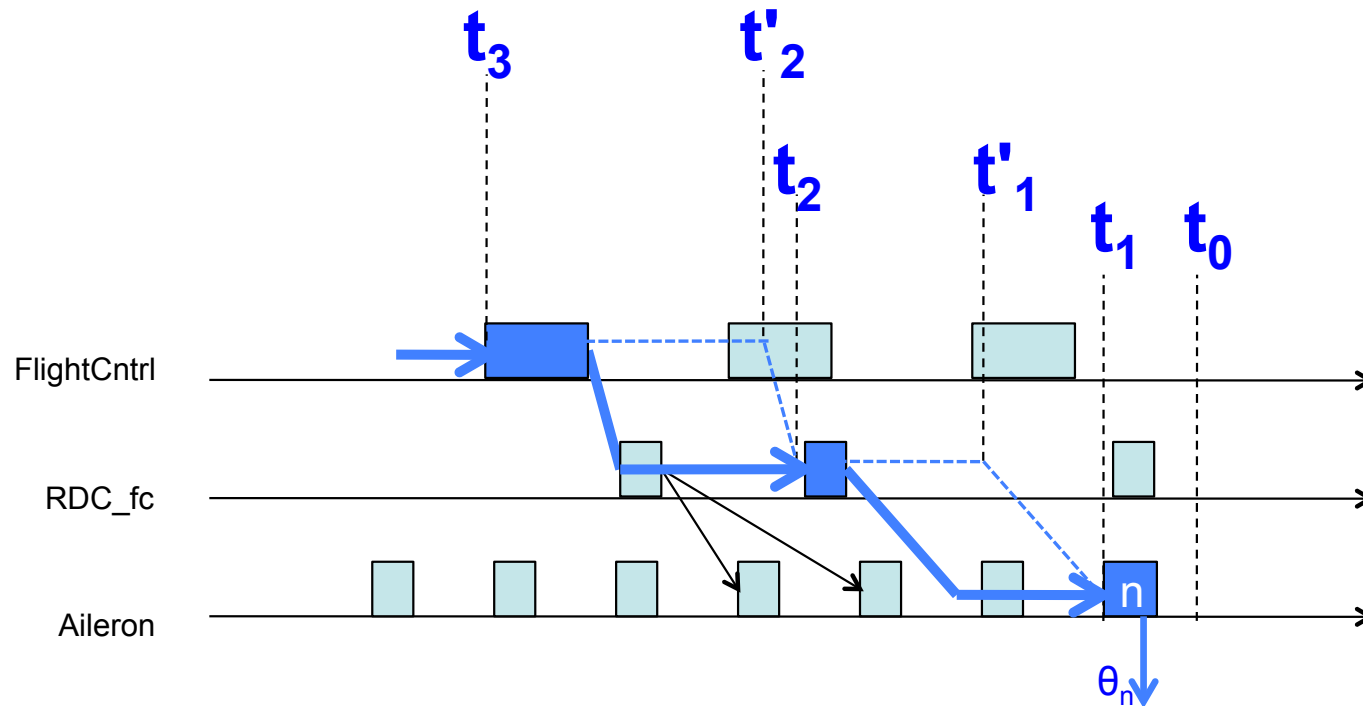
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Case study recall



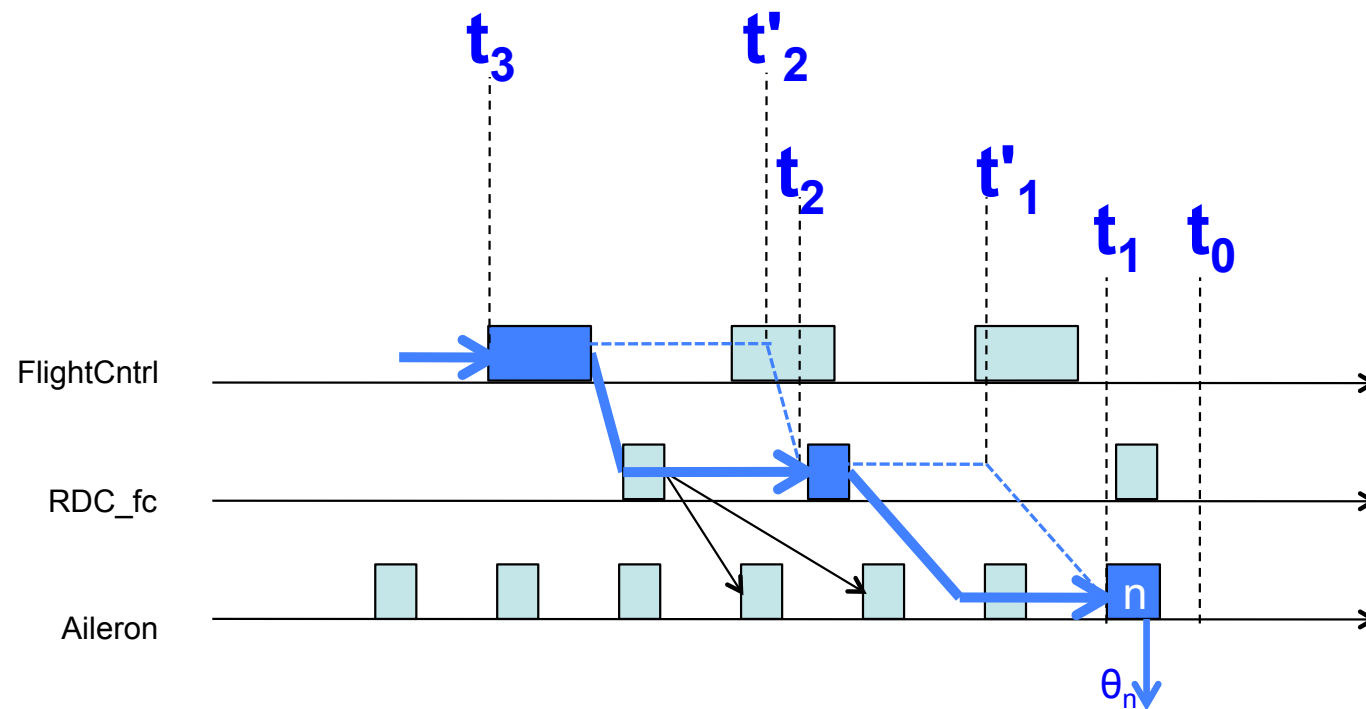
The modeling begins at the end
(freshness characterizes the output of the chain w.r.t. to the input)
⇒ Focus on the end of the chain

Case study recall



- t_0 = (arbitrary) date at which the output is observed
- n = occurrence of task “*Aileron*” which produces the output at t_0
- t_1 = date at which “*Aileron*[n]” begins and reads its input
- $t_1 - t'_1$ = communication time from “*RDC_fc*” to “*Aileron*”
- ⇒ t'_1 = date at which the output of “*RDC_fc*” is observed
- and so on...

Case study recall



⇒ Question: which constraints to characterize $n, t_1, t'_1, t_2 \dots$ from t_0 ?

Module (including sensors and actuators) modeling

- A module M_i is only characterized by an offset O_i
- Modules, sensors and actuators are asynchronous
- \Rightarrow each O_i can be arbitrarily chosen

\Rightarrow Constraints (case-study):

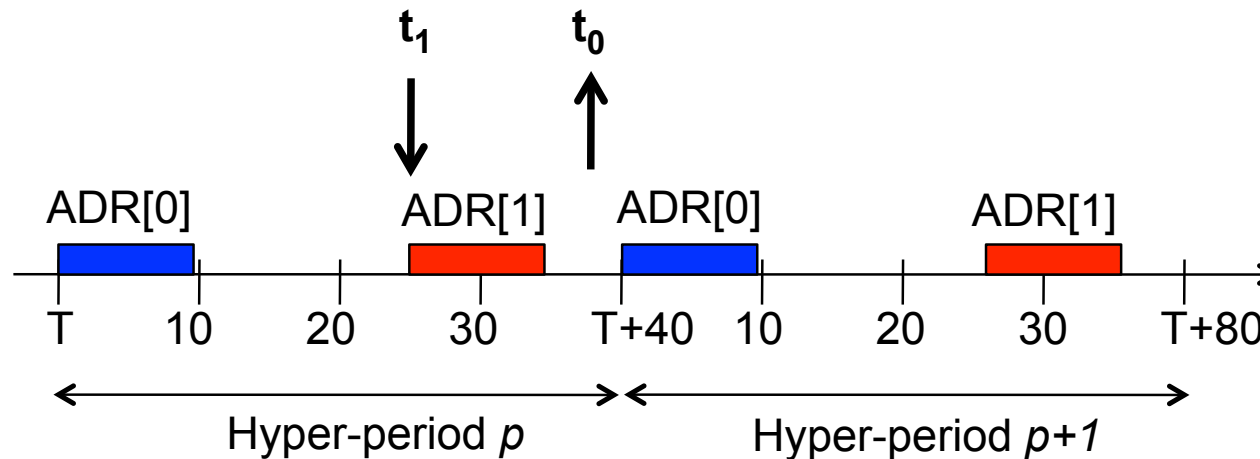
$$\begin{aligned} O_{Aileron}, O_{RDC1}, O_{M1} \dots &\in \mathbb{R} \\ 0 &\leq O_{Aileron} \leq H \\ 0 &\leq O_{RDC1} \leq H \\ 0 &\leq O_{M1} \leq H \\ &\dots \end{aligned}$$

where H is the highest hyper-period of the system ($H = 40$ in the case-study)

Task modeling

- a task is characterized by a set of jobs in the hyper-period of its module

Example: *ADR* (2 jobs in 40ms): $[0, 10]$, $[25, 35]$



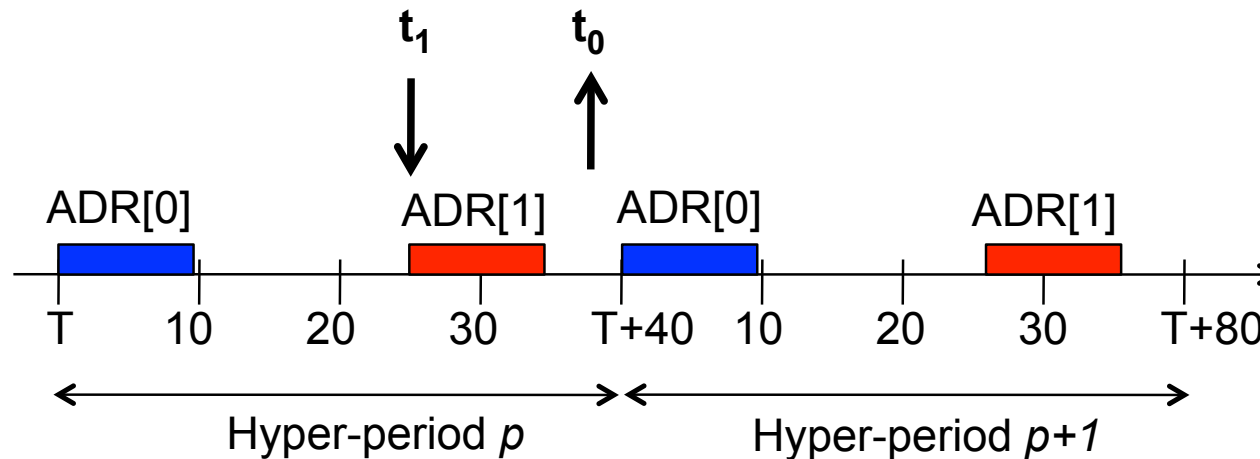
Problem:

- t_0 the date at which the output is observed
- what constraints to determine which job produces the output and the date t_1 from t_0 ?

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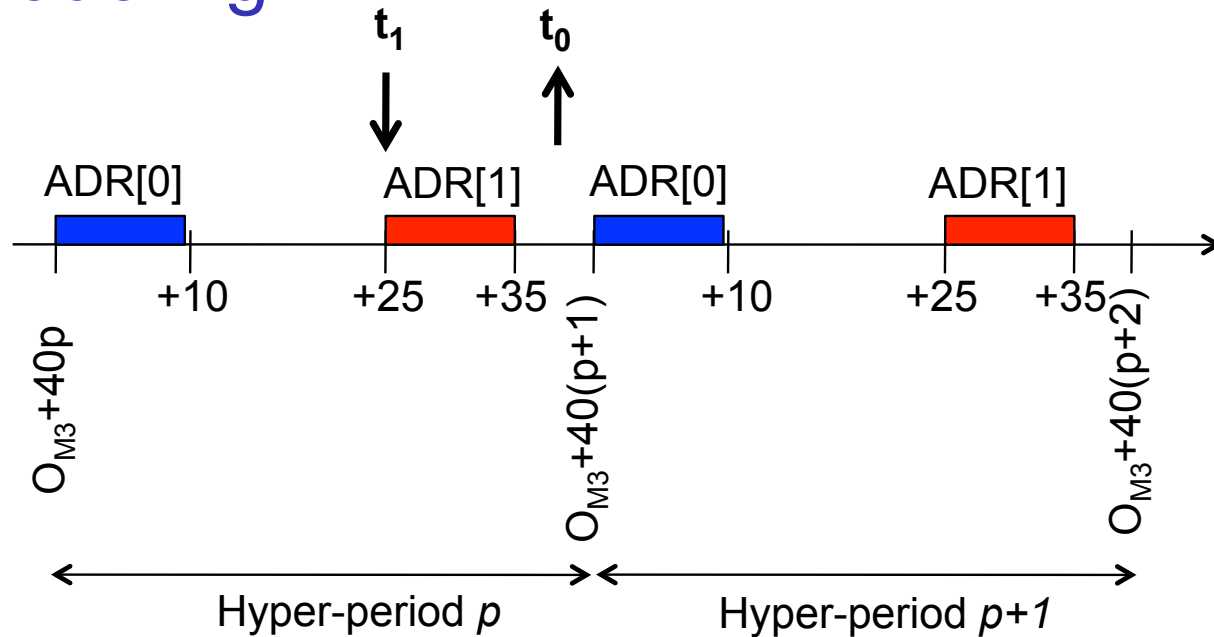
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Problem:

- t_0 the date at which the output is observed
- what constraints to determine which job produces the output and the date t_1 from t_0 ?

Task modeling



Let:

- $p \in \mathbb{N}$ (index of the current hyper-period at t_0)
- $B_{ADR[0]}, B_{ADR[1]} \in \{0, 1\}, B_{ADR[0]} + B_{ADR[1]} = 1$

Then:

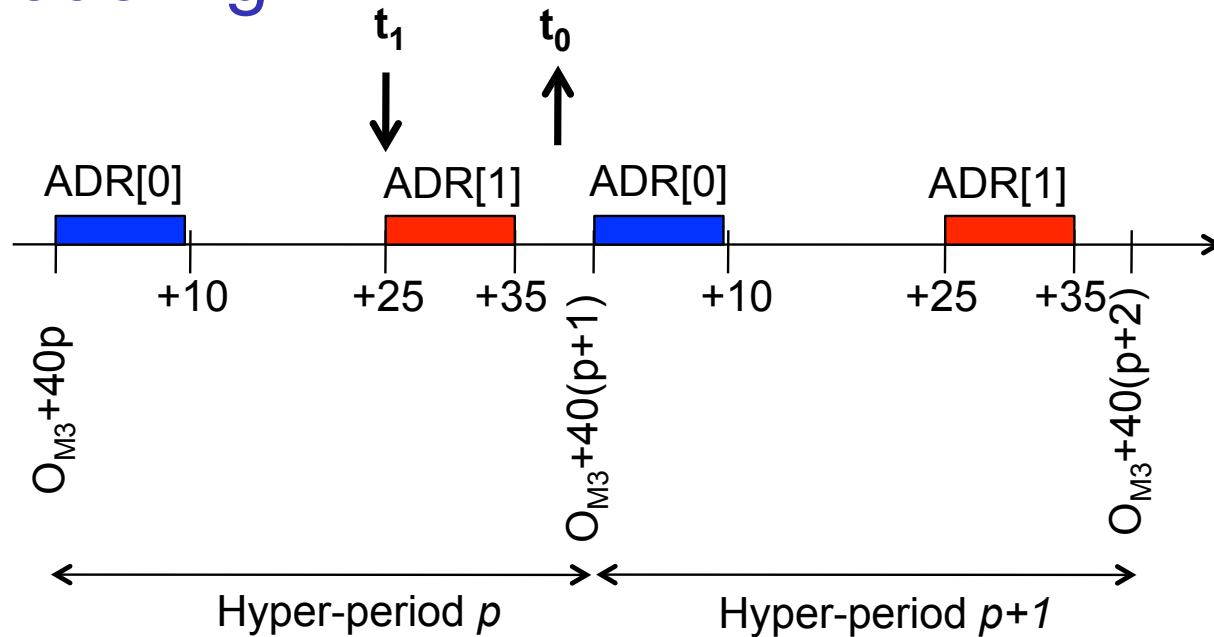
$$t_0 \geq O_{M3} + 40p + 0B_{ADR[0]} + 25B_{ADR[1]}$$

$$t_0 < O_{M3} + 40p + 35B_{ADR[0]} + (40 + 10)B_{ADR[1]}$$

(recall: a job can produce its output at anytime in its time interval)

$$t_1 = O_{M3} + 40p + 0B_{ADR[0]} + 25B_{ADR[1]}$$

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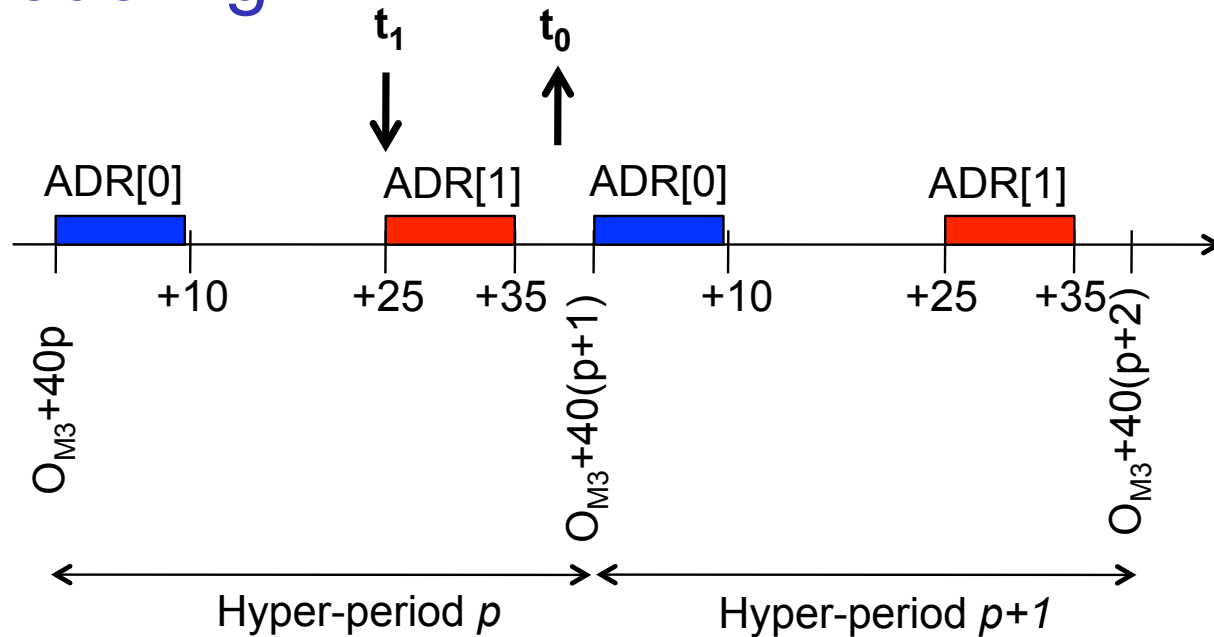
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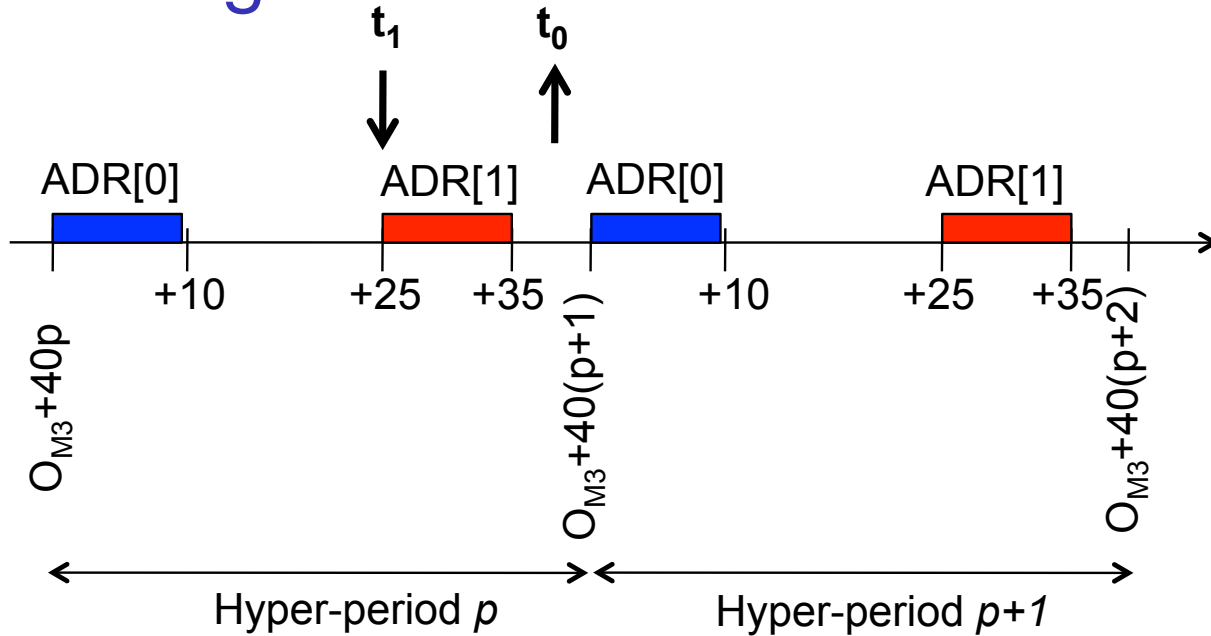
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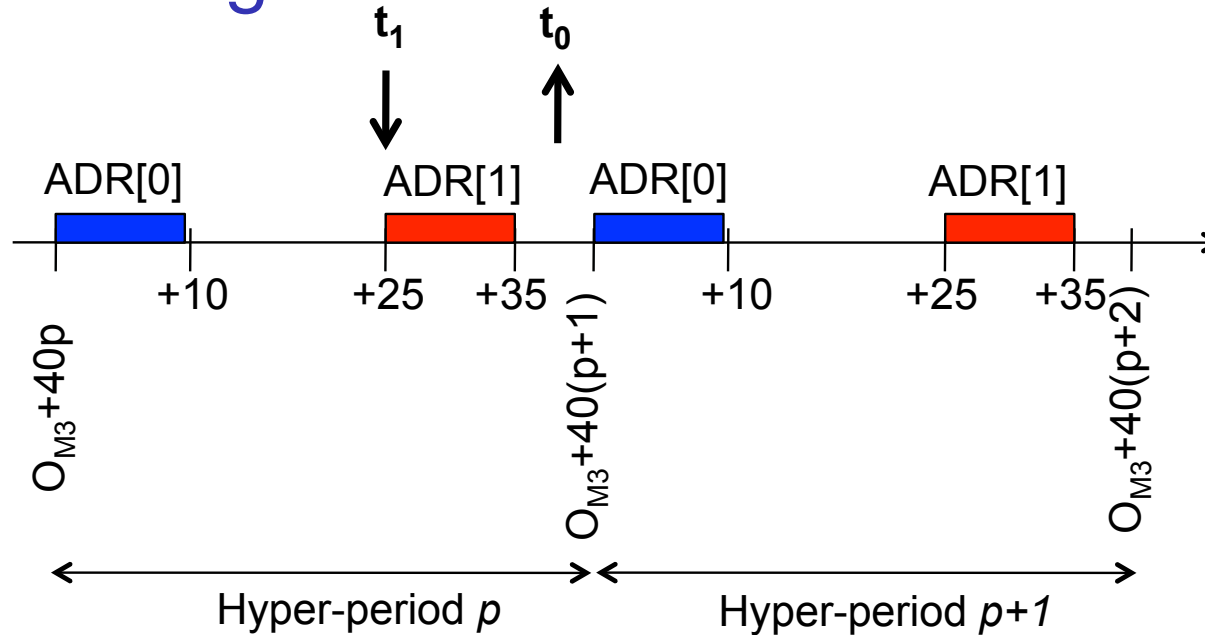
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Task modeling

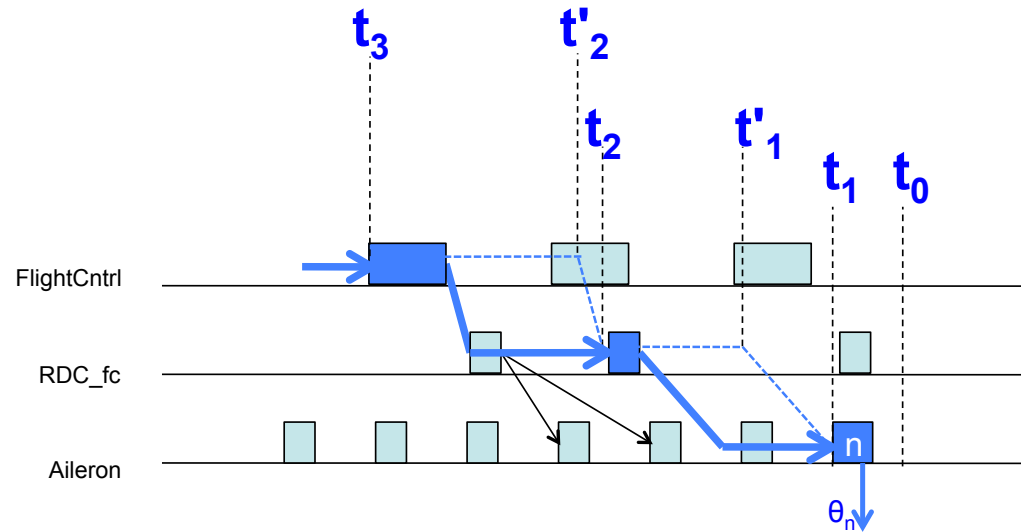
All solutions

$$(p, B_{ADR[0]}, B_{ADR[1]}, t_1) \in \mathbb{N} \times \{0, 1\} \times \{0, 1\} \times \mathbb{R}$$

satisfying the previous constraints characterize possible scenarios leading to the observation of the output at t_0 .

Task modeling

Back to the case-study:



$$t_0 \geq O_{Aileron} + 5p + 0B_{Aileron}[0]$$

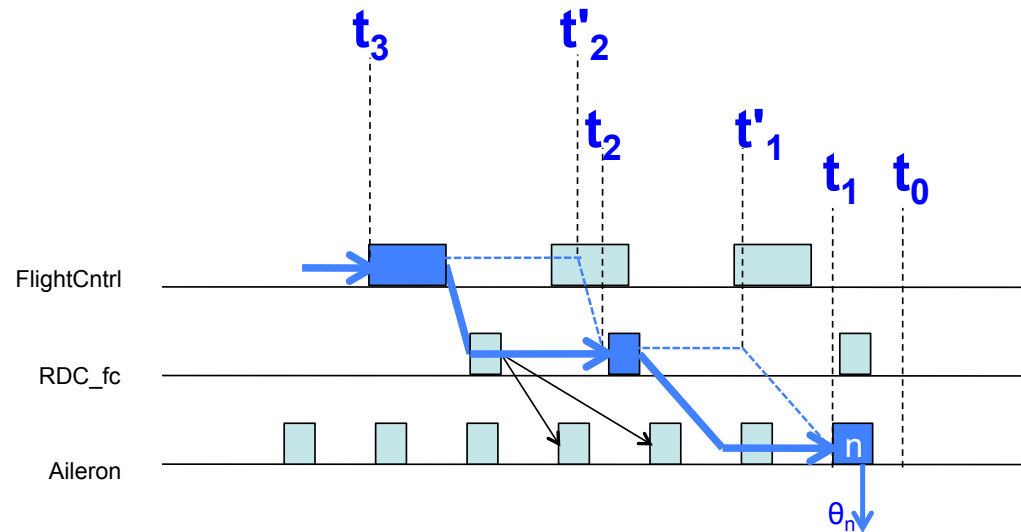
(recall: *Aileron* has only one job in its hyper-period (5ms))

$$t_0 < O_{Aileron} + 5p + 6B_{Aileron}[0]$$

(recall: the length of *Aileron* is 6ms)

$$t_1 = O_{Aileron} + 5p + 0B_{Aileron}[0]$$

Communication modeling



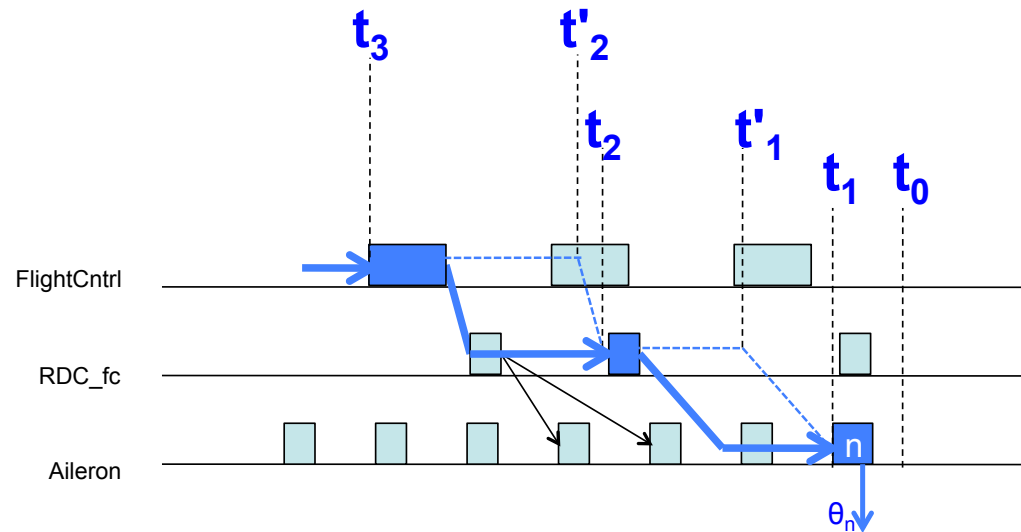
Let

- δ_{min} = the minimum communication time
- δ_{max} = the maximum communication time

⇒ Constraints:

$$t'_1 + \delta_{min} \leq t_1 \leq t'_1 + \delta_{max}$$

Communication modeling



Let

- δ_{min} = the minimum communication time
- δ_{max} = the maximum communication time

⇒ Constraints:

$$t'_1 + \delta_{min} \leq t_1 \leq t'_1 + \delta_{max}$$

Latency requirement modeling

And so on ... up to

$$t_8 = O_{Air_sensor} + 5p_8 + 0B_{Air_sensor}[0]$$

(t_8 is the date at which the total pressure corresponding to the Aileron position at t_0 is read; p_8 is the number of the corresponding hyper-period of the Air sensor)

⇒ The freshness expression:

$$F = t_0 - t_8$$

⇒ The worst case freshness is obtained on a particular behavior maximizing F .

⇒ Optimization problem:

maximize: F

Latency requirement modeling

And so on ... up to

$$t_8 = O_{Air_sensor} + 5p_8 + 0B_{Air_sensor}[0]$$

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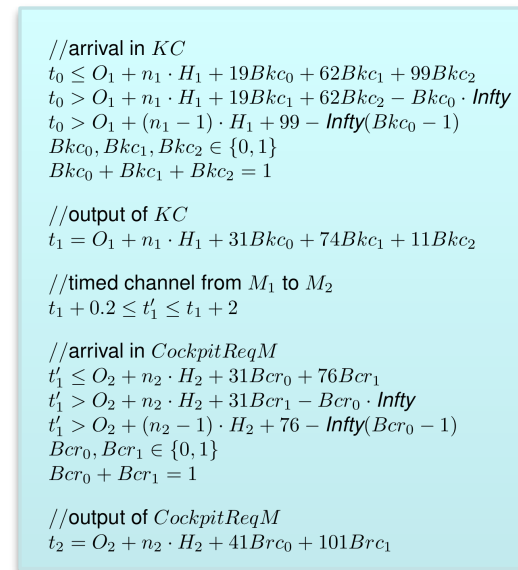
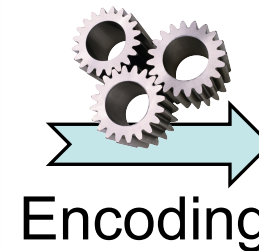
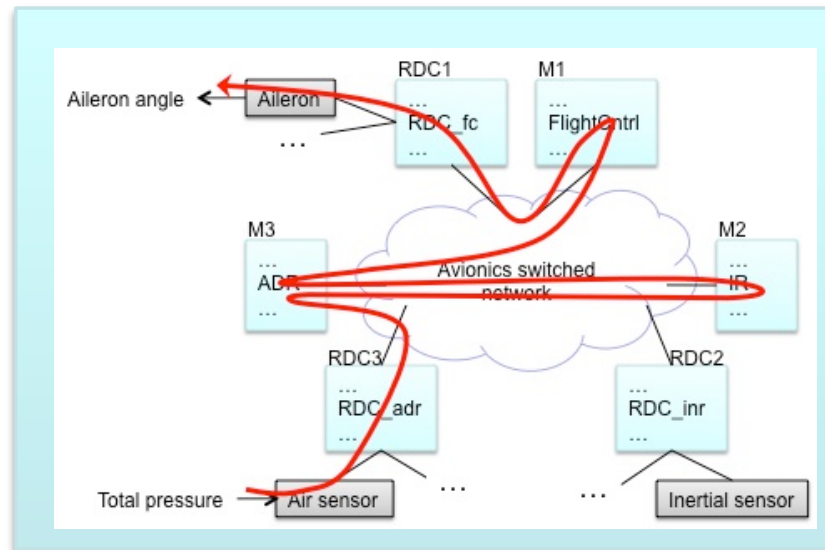
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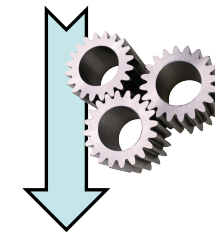
The tool chain



System model + WCF requirement

MILP model

LP-solve



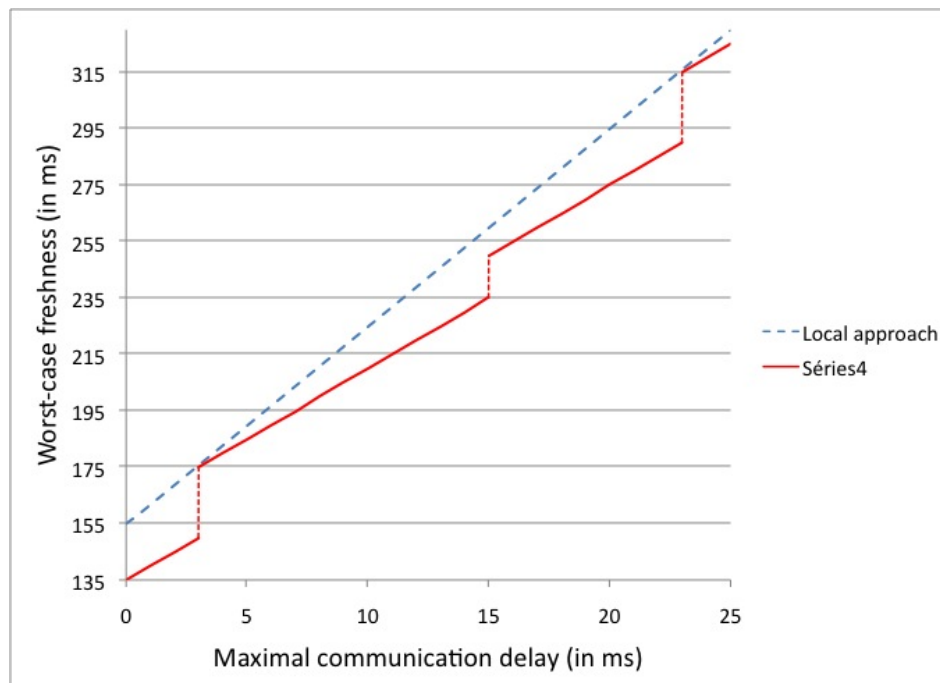
Worst-case latency +
a worst-case scenario

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Results on the case study: global v.s. local approach

- global approach against the local one (i.e. sum of the local worst case)
- by varying the upper bound of the communication delays through the network



- red line = global approach
- dashed line = local approach

End-to-end freshness of aileron angle

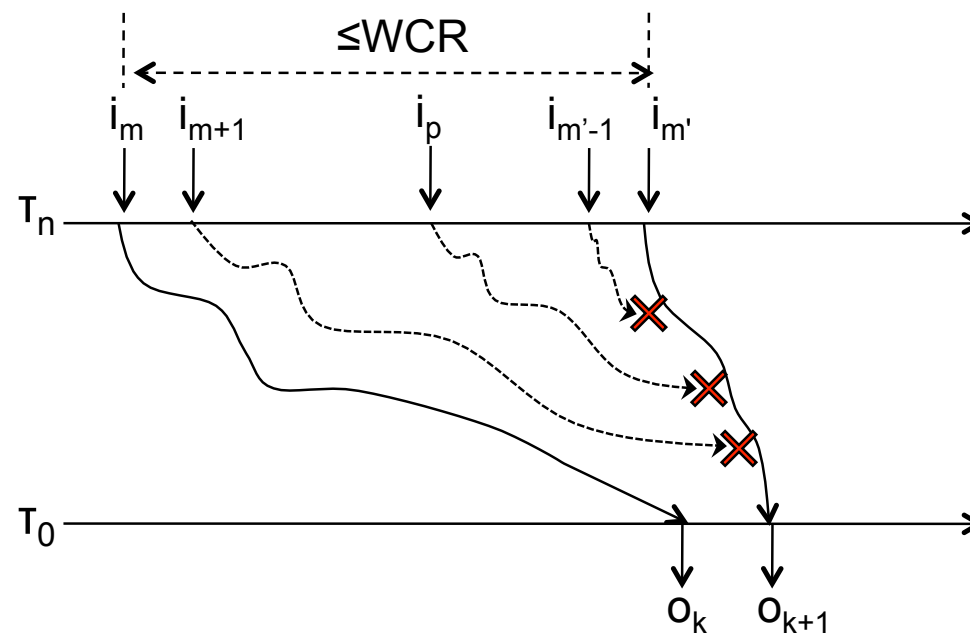
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End-to-end reactivity requirement

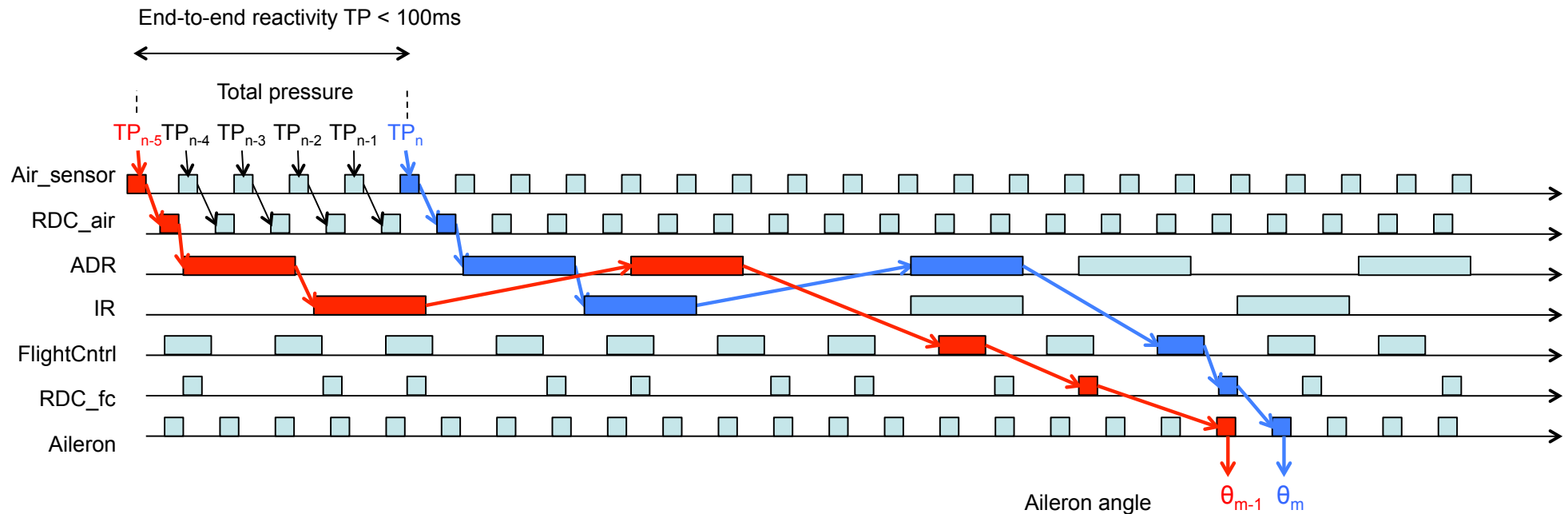
End-to-end reactivity =

the minimal duration of an input signal, in order to be taken into account at the output of the chain



- i_m impacts o_k , $i_{m'}$ impacts o_{k+1}
 - i_{m+1} to $i_{m'-1}$ do not impact the output (overwritten in the chain)
- ⇒ Worst Case Reactivity $\geq \text{date}(i_{m'}) - \text{date}(i_m)$

End-to-end reactivity requirement

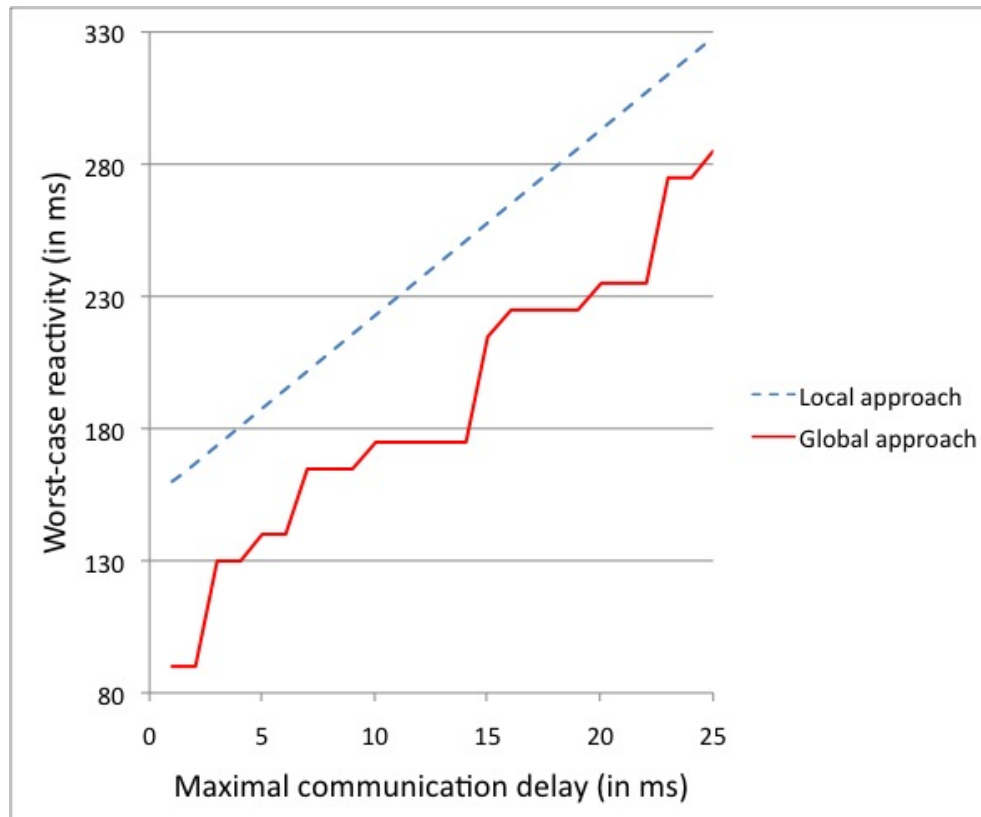


Approach:

- backtrack dependencies of two successive outputs
 - ▶ $\theta_m \rightsquigarrow TP_n$
 - ▶ $\theta_{m-1} \rightsquigarrow TP_{n'}$ (in the figure $n' = n - 5$)
- use the same constraints / variables as for freshness analysis
- maximize: $date(TP_n) - date(TP_{n'})$

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End-to-end reactivity of total pressure

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Conclusion and next work

Conclusion

- An efficient method for worst-case end-to-end freshness and reactivity analysis
 - Extendable for best-case analysis
 - Scalability:
 - ▶ takes less than 1 minute on the case-study
 - ▶ functional chain in realistic avionic systems contains at most 10 jumps from a task to another one (similar to the case-study)
- ⇒ seems to be scalable

Next work

- Take into account the internal behavior of the tasks (i.e. latencies induced by the functional behavior of a task)

Thank you for your attention
(and many thanks to Pierre-Loïc Garoche)